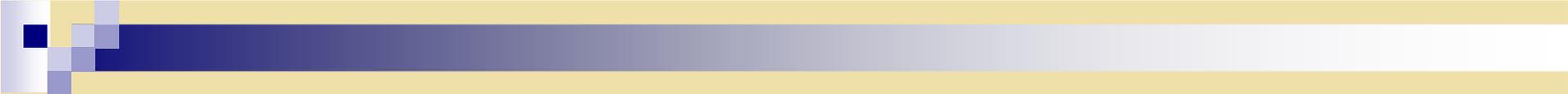




Budapest University of Technology and Economics

TWO-DISC MACHINE

Made by:
Attila Kovács



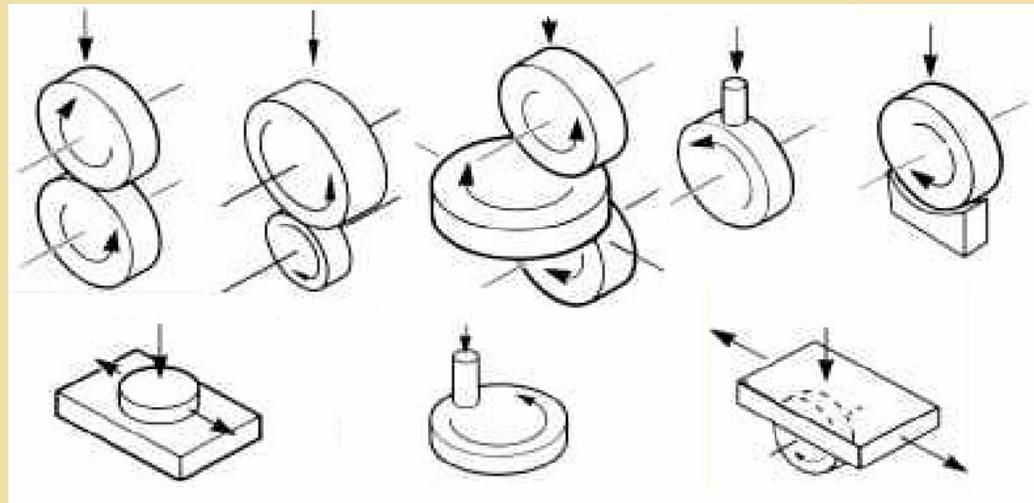
Introduction:

The process of a Tribological system is complex, and it's hard to describe theoretically.

Experimental equipments are usually used to understand **frictional** and **wear behaviour**, **carrying capacity** and **lifetime** in sliding and rolling applications.

Using specimens with simple shape:

- Advantages: easy, economical and precise production of geometry (plain, cylinder, cone, ball, etc.)
- Contact relations: sliding, rolling, **sliding&rolling** (constant or changing direction in moving)
- Commonly used specimen-pairs: pin-on-disc, ball-on-disc, four ball, block-on-ring, pin-on-plate, **two-disc**, ...



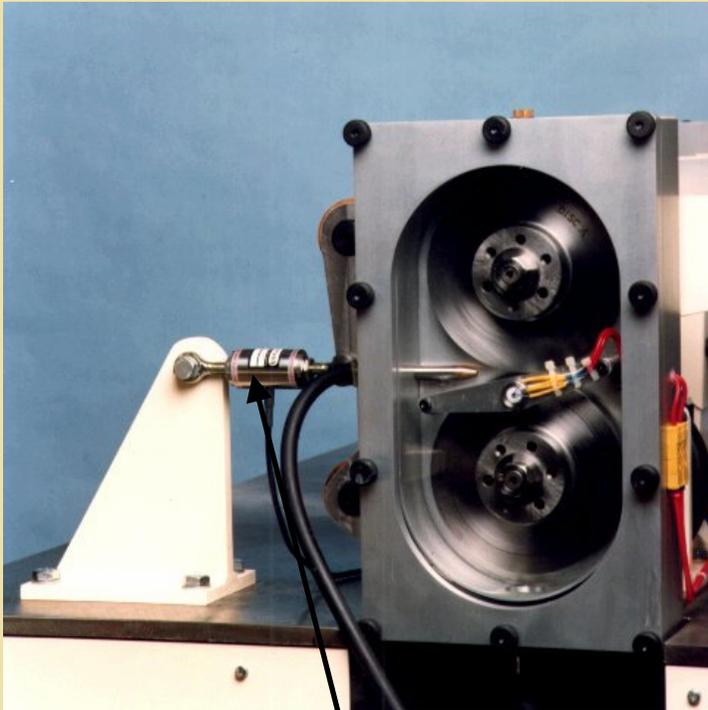
We use model tests to study:

- surface fatigue
- wear
- and to evaluate the coeff. of friction between specimens.

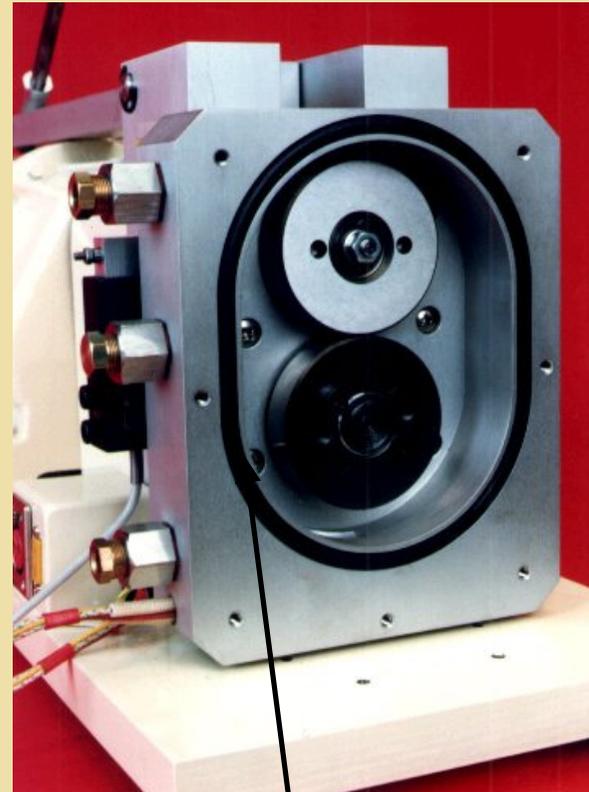
The friction coefficient can be calculated, if we know:

- the rotational speed (n_1)
- the load (F_1)
- the geometry ($\sphericalangle d_1$)
- the torque, acting on the shaft (M_1)

Two-disc machines (from industry): (PLINT Tribology Inc.)



Infrared sensors for
measuring the contact
temperature



Sealed equipment,
lubrication applicable



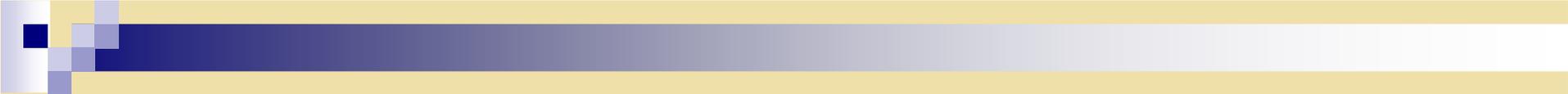
double-side driving



single driving (one side)

Design conditions:

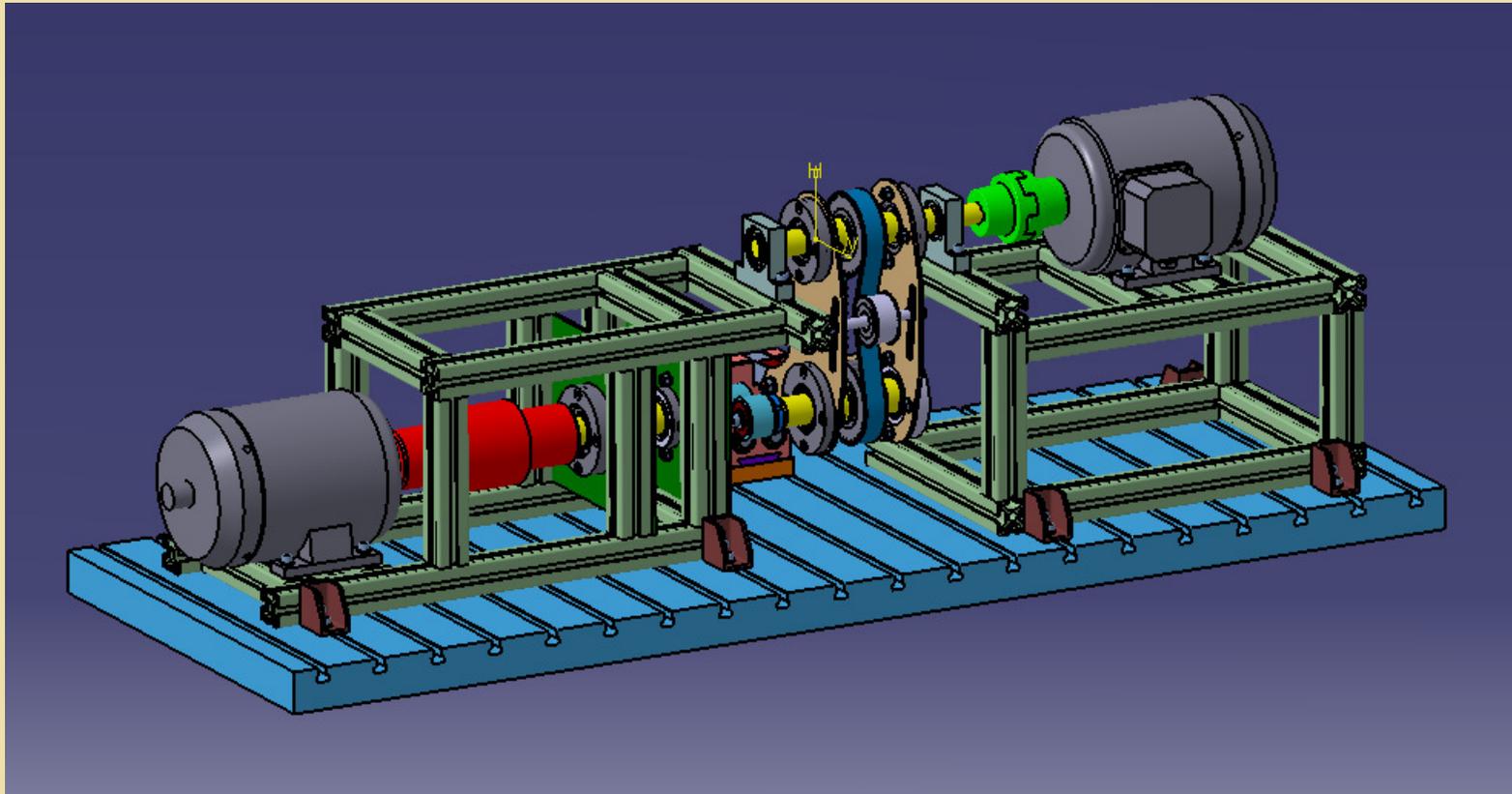
- Load = 2000 [N]
- Specimen diameter = 50 [mm]
- max. coeff. of friction = 0,8
- max. width of specimen = 50 [mm]
- max. revolution = 1000 [1/min]
- max. slip = 10 [%]



Design aims:

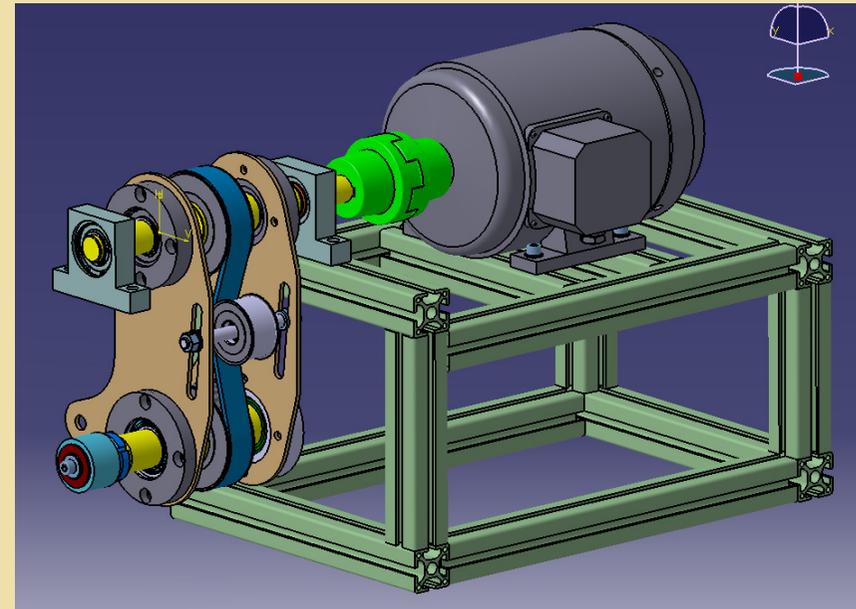
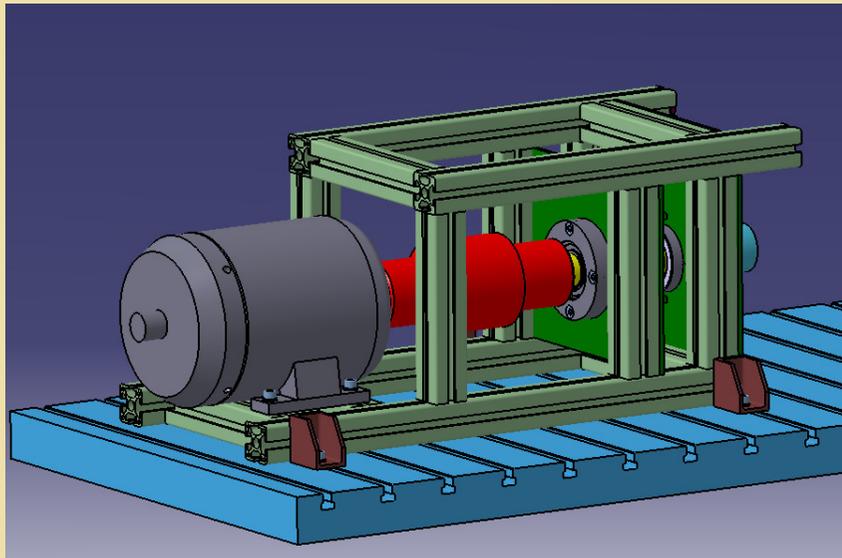
- To use standardized elements (nuts, screws, bearings, bearing-housing, Seeger-rings,...)
- To use Alu profiles for the rack
- Easy to change the specimens
- To use Different specimen are being measured
- To be able to measure and set the revolution
- To be able to measure the frictional moment
- To be able to measure the contact temp
- Easy to mount

The designed machine:



Two separated parts:

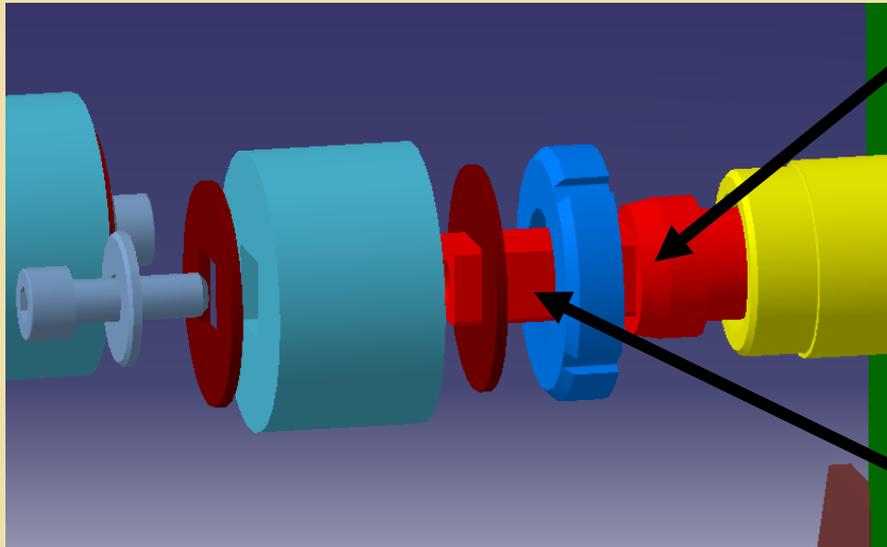
I. Moving unit with the tilting arm



II. Stationary unit fasten to the base

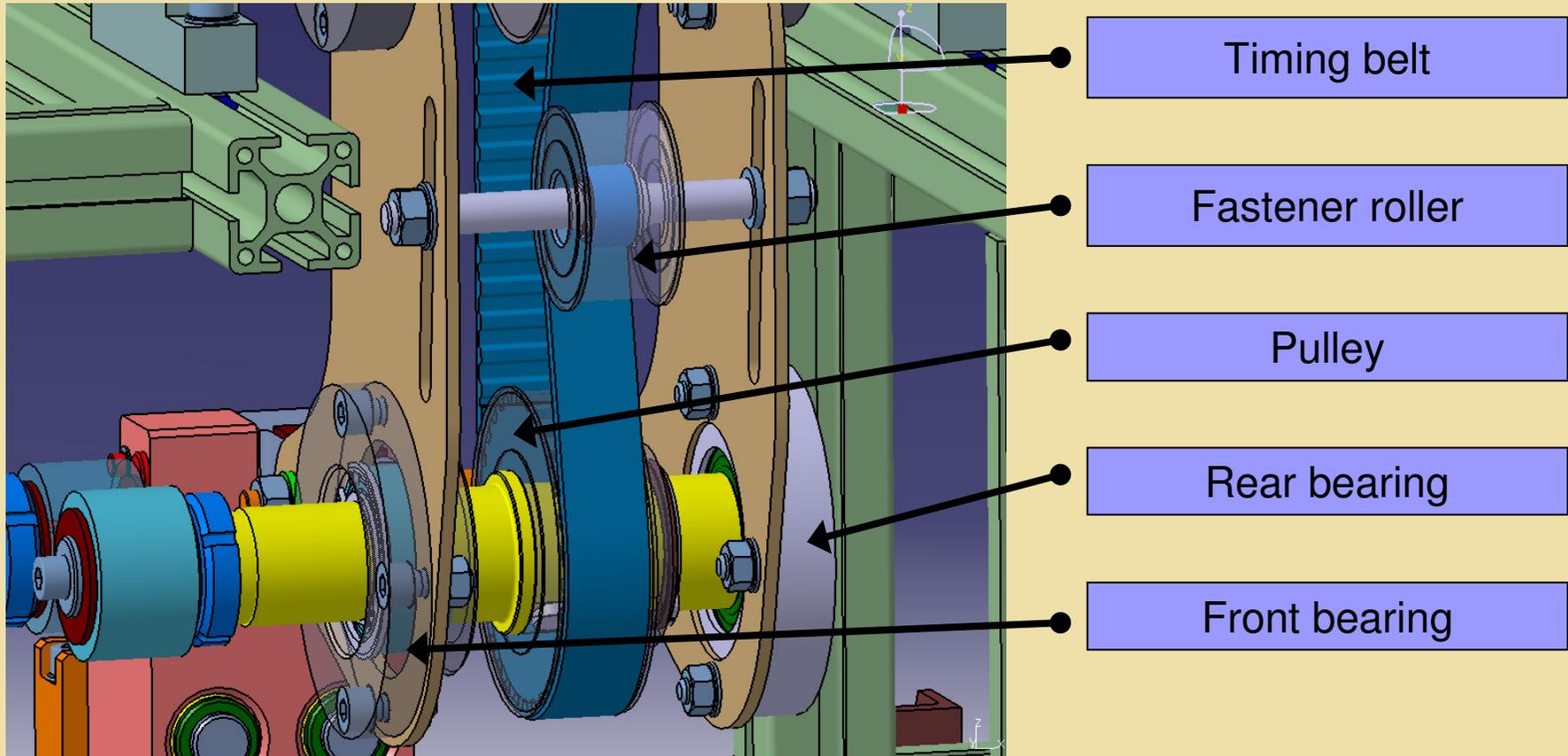
Parts of moving unit:

Speciement clamping



- Mounting from one side
- Cones are fasten the shaft against axial moving
- First the specimen mounting and after that the specimen-shaft
- Fixing by non-circular profile

Parts of tilting arm:



Timing belt:

Type: AT 10

Width: 25 mm

Length: 1120 mm

SIEGLING
BELTING



Bearing units:



MISUMI Group Inc.

Type:

2 db BGCRB (6006_2RS)

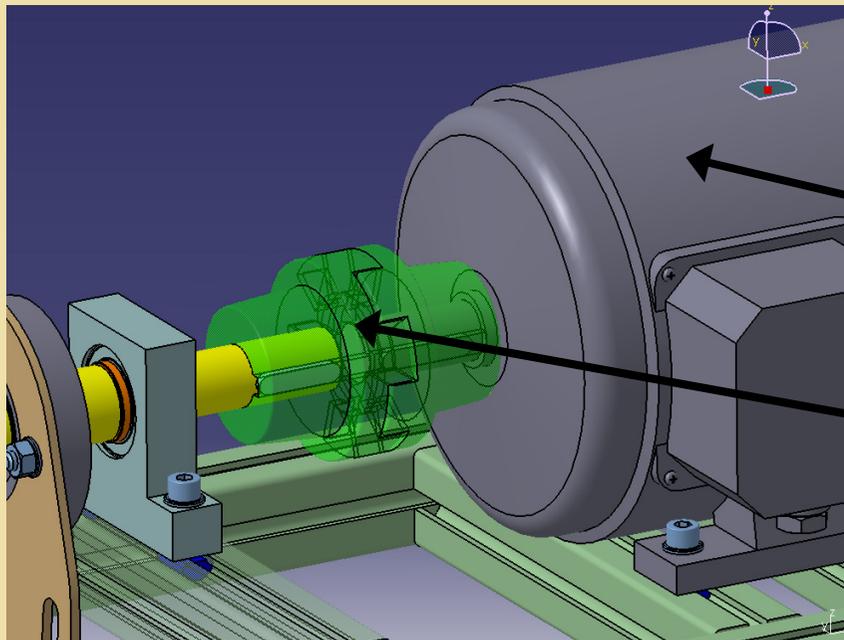
2 db SBACR (6007_2RS)

2 db SBACY (NA4907_2RS)

1 db NA4901_2RS needle-roller bearing



Driving unit:



3 phase assynchronous motor

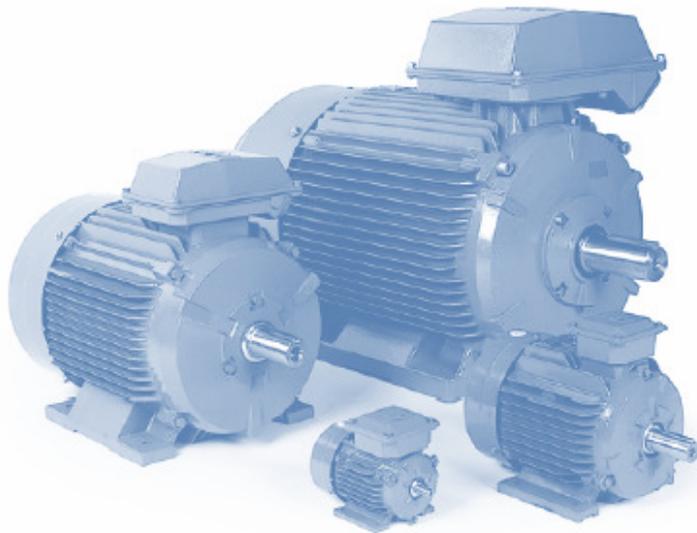
Rotex coupling

The ABB logo is displayed in a bold, red, sans-serif font. The letters 'A', 'B', and 'B' are connected, with the 'A' having a distinctive shape with a horizontal bar.

3 phase asynchronous motor :

General Purpose Cast Iron Motors

Totally enclosed squirrel cage three phase low voltage motors,
Sizes 71 - 355, 0.25 to 250 kW



Type: M2QA_90S4A

$P = 1,1 \text{ kW}$

$n = 1400 \text{ 1/min}$



Coupling:

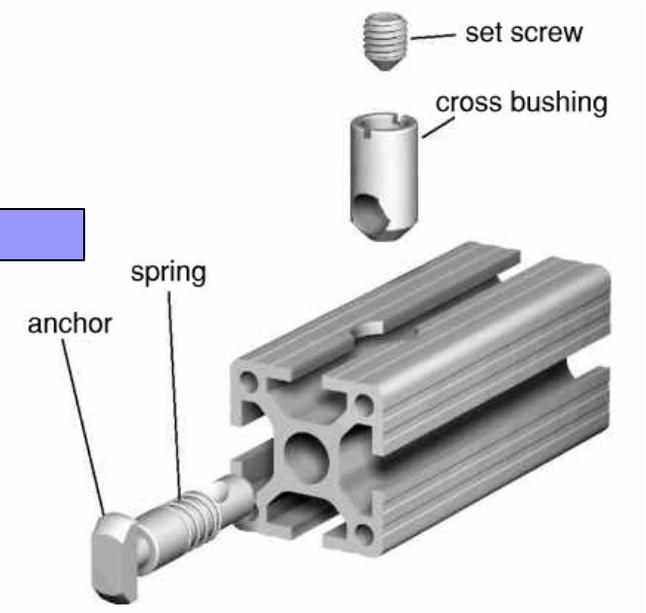
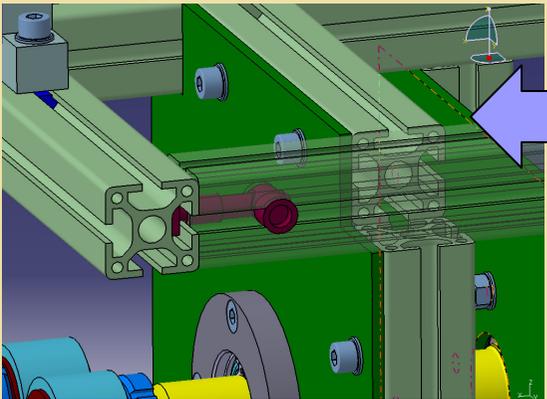
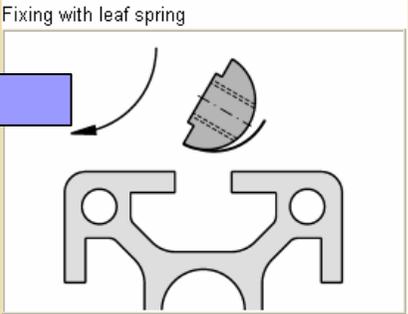
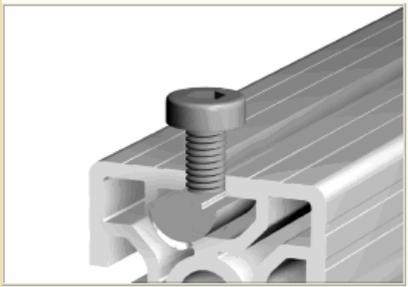
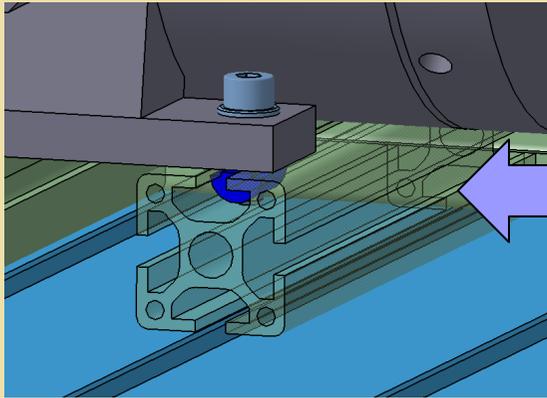
$M = 15 \text{ Nm}$

$\varnothing d1 = 24 \text{ mm}$

$\varnothing d2 = 25 \text{ mm}$

Frame structure of the test rig:

Clamping elements





Torque meter:

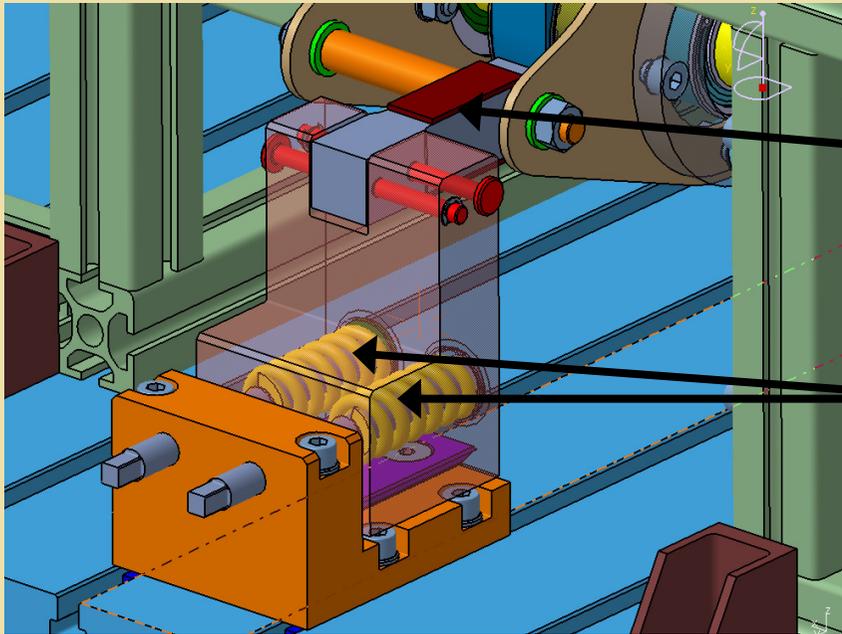
Type: RADEX_NC_22/20

Max. measuring range: 20 Nm

Working temp. range: 0..55 °C

- Integrated revolution measuring
- Minimized internal power loss
- High measuring frequency
- Widely applicable

Parts of loading unit:



Load cell

Loading helical springs

Load cell:



Type: SSB_AJ_250

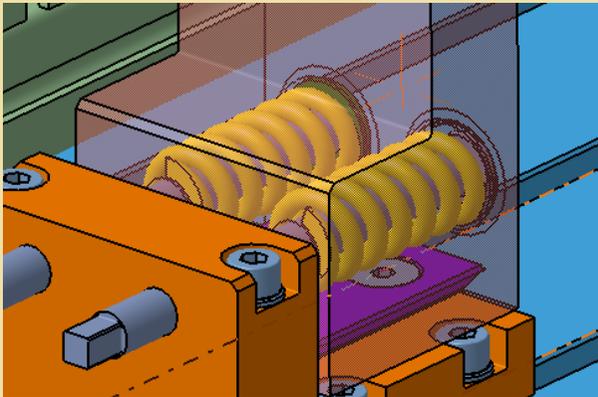
Range: 0...2500 N

Working temp. range: -55..90 °C

Typicals:

- Sealed
- Temperature compensated
- Accuracy < 0,01 %
- Small geometry
- Easily connected

Helical spring



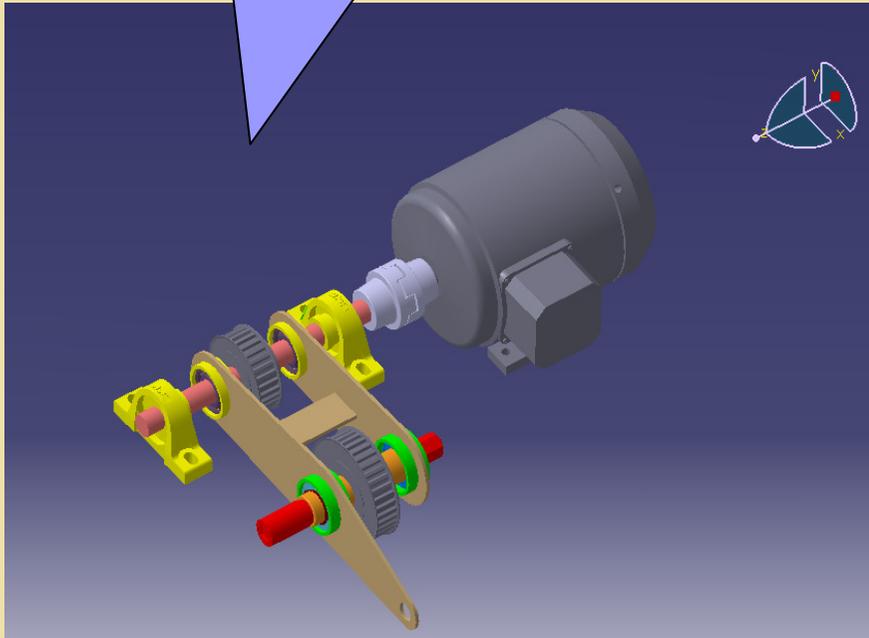
DIN 2098 standardized:

Dimensions:

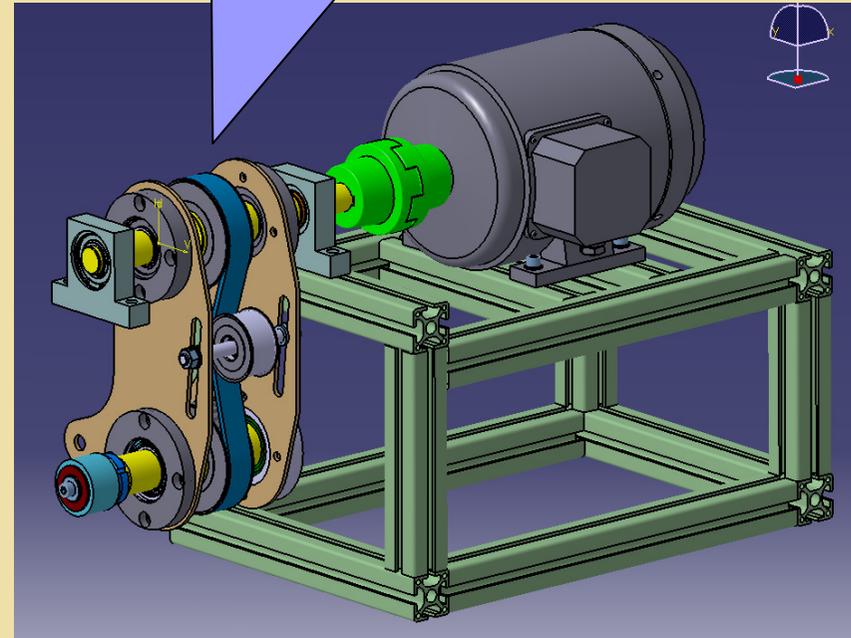
DIN 2098 – 5x25x80

Comparing the first and the final design:

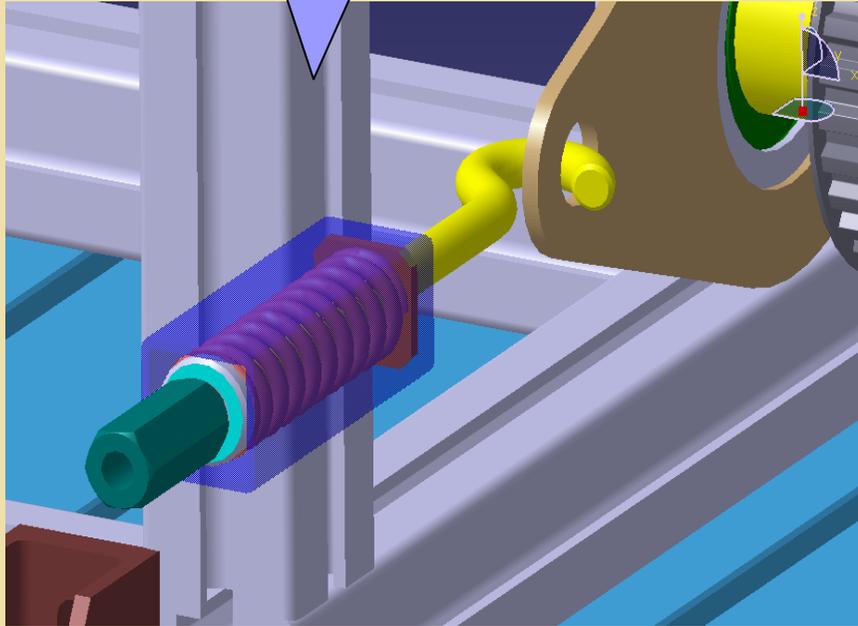
- Welded ring
- Y bearings
- Load applied at the end of the arm
- Stiffening rib



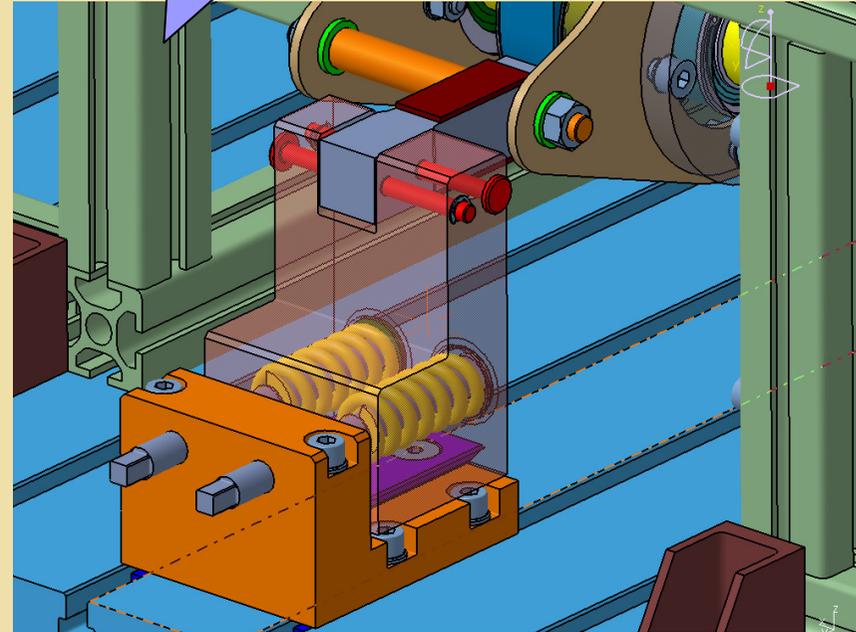
- Bolted joint connection
- Deep groove ball bearings
- Loading unit is better
- No stiffening rib
- Belt tension roller applied



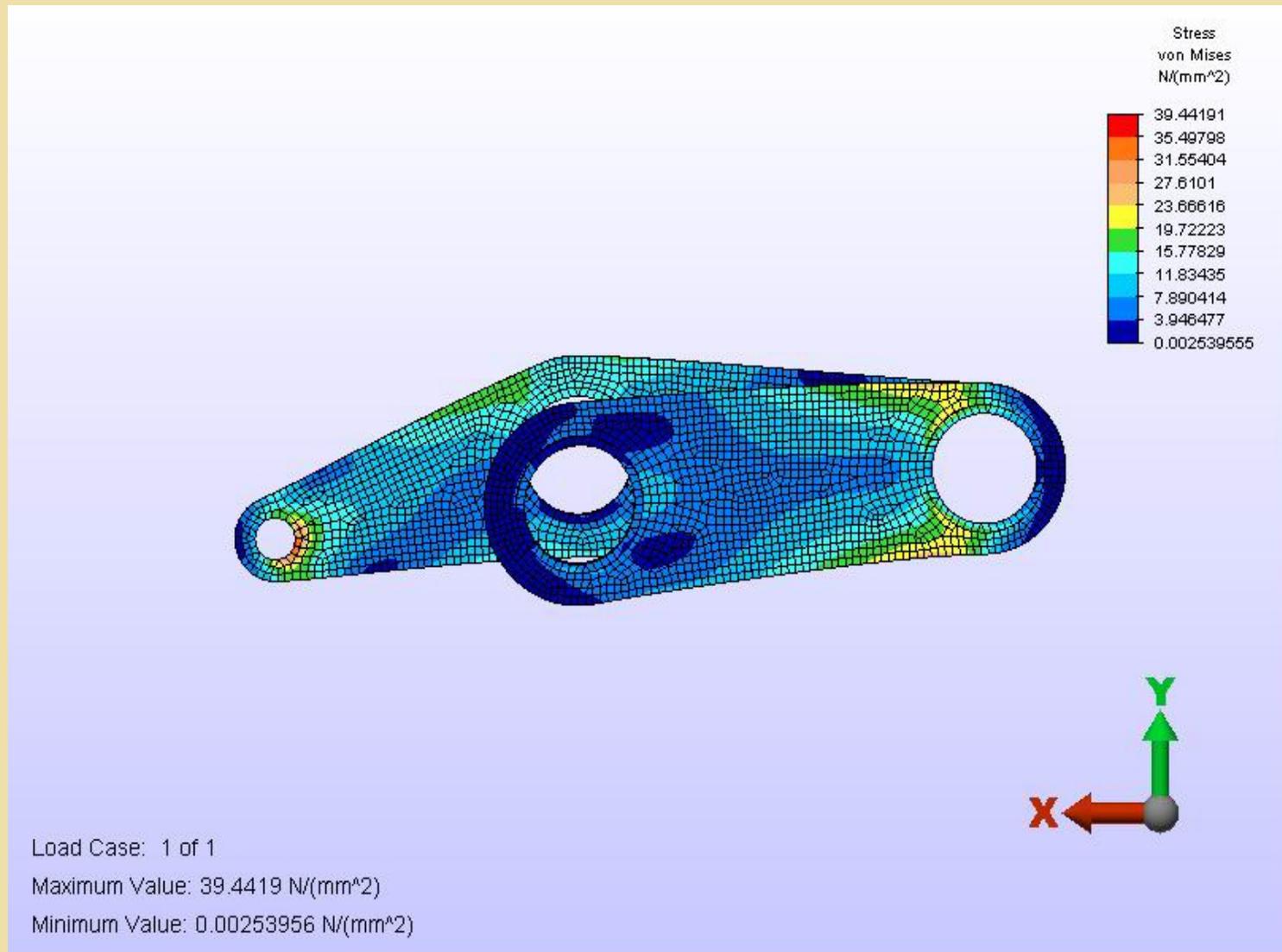
- Easy to joint solution



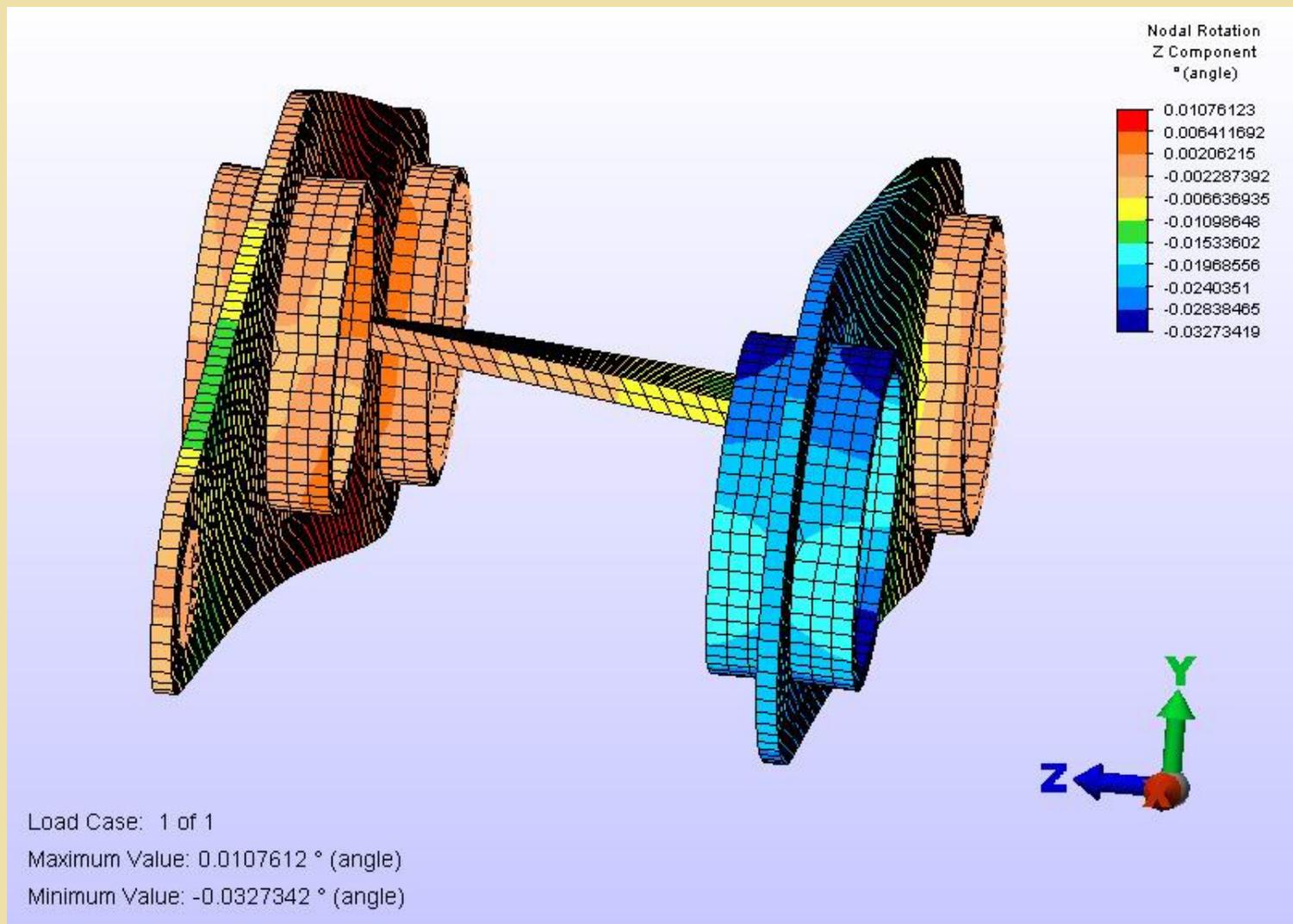
- Load application is better
- Easy to set the load (thread)
- Additional load!



FE Analysis: Von Mises Stress



Angular distorsion (round axis Z):



Calculation:

Frictional moment - power loss

Bearing	6205
d, mm	25
D, mm	52
d_m , mm	38.5
n, r/min	1000
v , mm ² /s	294
F_r , N	2000
F_a , N	0
H_{EHL}	0.05
<input checked="" type="radio"/> Grease	
<input type="radio"/> Oil spot	
<input type="radio"/> Oil bath	
<input type="radio"/> Oil jet	
H, mm	
K_{rs}	6e-8
	Calculate
W_s , W/°C	5
	Calculate

Rolling frictional moment

$\Phi_{ish} \Phi_{rs} M_r$, Nmm 39.7

Sliding frictional moment

M_{sl} , Nmm 19.8

Frictional moment of seals

M_{seal} , Nmm 0

Frictional moment of drag losses

M_{drag} , Nmm 0

Total frictional moment

M, Nmm 59.6

Power loss

N_R , W 6.24

Starting torque

M_{start} , Nmm 59.5

[Extra info](#)

Temperature increase

ΔT , °C 1.25